

FINITE ELEMENT METHOD FOR SECOND-ORDER LINEAR DIFFERENTIAL EQUATIONS OF ELLIPTIC TYPE

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Abstract

In this work, an integral equation is presented for solving second-order linear differential equations of elliptic type using the finite element method. In addition, basis functions of two variables are constructed in a bounded domain on the plane.

Key words. approximation, basis functions, finite elements, PDE, mixed boundary value problem.

We consider a linear partial differential equation of the second order

$$-\sum_{i=1}^2 \frac{\partial}{\partial x_i} c \frac{\partial u}{\partial x_i} + \sum_{i=1}^2 b_i \frac{\partial u}{\partial x_i} + au = f \tag{1}$$

in a domain $\Omega = [0,1] \times [0,1]$ bounded on a plane. Let the classical solution $u(x_1, x_2)$ satisfying the mixed boundary conditions

$$u = u_D, \quad x \in \Gamma_0, \tag{2}$$

$$c \frac{\partial u}{\partial \nu} + \sigma u = \mu, \quad x \in \Gamma_1 \tag{3}$$

exist and be unique to equation (1). Here, c, a, f are scalar functions, $b = (b_1, b_2)$ is a vector function, a sufficiently smooth function of variable $x = (x_1, x_2) \in \bar{\Omega}$, ∇ is a gradient differential operator, $c(x) > 0$ ($x \in \bar{\Omega}$), $\Gamma = \partial\Omega = \Gamma_0 \cup \Gamma_1$, $\Gamma_0 \cap \Gamma_1 = \emptyset$, u_D, σ, μ are given continuous functions, $\nu = \nu(x)$ is the external unit normal vector at $x \in \Gamma_1$.

The following theorem holds.

Theorem 1. Constructing the approximate solution u_h of the mixed boundary value problem (1)–(3) using the finite element method leads to finding such a function $u_h \in V_h$ in which the equality

$$\begin{aligned} & \int_{\Omega_h} (c \nabla u_h \cdot \nabla \vartheta_h + b \cdot \nabla u_h \vartheta_h + a u_h \vartheta_h) dx + \int_{\Gamma_1^h} \sigma u_h \vartheta_h dx \\ & = \int_{\Omega_h} f \vartheta_h dx + \int_{\Gamma_1^h} \mu \vartheta_h dx \end{aligned}$$

is valid for an arbitrary $\vartheta_h \in V_h^0$ (see: [1]). Where, $\Omega_h = \bigcup_{\tau \in \tau_h} \tau$, τ_h is the partition of the domain Ω into Lagrangian finite elements of the same type τ , Γ_0^h, Γ_1^h is the parts of the boundary of the domain Ω_h corresponding to Γ_0 and Γ_1 ,

$$V_h = \{ \vartheta \in S_h : \vartheta(x) = u_D(x), x \in \gamma_h \},$$

$$V_h^0 = \{ \vartheta \in S_h : \vartheta(x) = 0, x \in \gamma_h \},$$

$$S_h = \left\{ \mathcal{G} \subset C(\overline{\Omega}_h) \mid H^1(\Omega_h) : \mathcal{G}|_{\tau} = P_{\tau}, \forall \tau \in \mathcal{T}_h \right\},$$

P_{τ} is the space of finite-dimensional functions in τ , \mathcal{T}_h is the set of interpolation nodes corresponding to Γ_0^h .

It is known that the approximate solution $u_h \in V_h$ of the mixed boundary value problem (1) – (3) is sought in the form

$$u_h(x_1, x_2) = \sum_{i=0}^m \sum_{j=0}^n \alpha_{ij} \varphi_{ij}(x_1, x_2), \quad (4)$$

here α_{ij} are unknown coefficients, and $\varphi_{ij}(x_1, x_2)$ are linearly independent functions.

The functions $\varphi_{ij}(x_1, x_2)$ satisfy the following conditions:

- i) φ_{ij} functions are piecewise-linear functions in domain Ω ;
- ii) $\varphi_{ij} \in C(\Omega)$ ($i = 0, 1, \dots, m, j = 0, 1, \dots, n$);
- iii) φ_{ij} ($i = 0, 1, \dots, m, j = 0, 1, \dots, n$) functions are satisfying the relation

$$\varphi_{ij}(x_p, x_q) = \begin{cases} 1, & p = i \text{ and } q = j, \\ 0, & \text{otherwise,} \end{cases}$$

i.e.,

$$\varphi_{ij}(x_p, x_q) = \delta_{ip} \delta_{jq} \quad (p = 0, 1, \dots, m, q = 0, 1, \dots, n),$$

where δ_{ip} and δ_{jq} are Kronecker symbols.

In this work, we construct two-variable trigonometric basis functions to find the approximate solution (4) in analytical form. For this, we will use the results obtained in the work [2].

Theorem 2. Piecewise-linear functions φ_{ij} are defined in the domain Ω have the form:

$$\varphi_{ij}(x_1, x_2) = \begin{cases} \frac{\sin(x_1 - x_{1,i-1}) \sin(x_2 - x_{2,j-1})}{\sin(x_{1,i} - x_{1,i-1}) \sin(x_{2,j} - x_{2,j-1})}, & x_{1,i-1} < x_1 < x_{1,i}, x_{2,j-1} < x_2 < x_{2,j}, \\ \frac{\sin(x_1 - x_{1,i-1}) \sin(x_2 - x_{2,j+1})}{\sin(x_{1,i} - x_{1,i-1}) \sin(x_{2,j} - x_{2,j+1})}, & x_{1,i-1} < x_1 < x_{1,i}, x_{2,j} < x_2 < x_{2,j+1}, \\ \frac{\sin(x_1 - x_{1,i+1}) \sin(x_2 - x_{2,j-1})}{\sin(x_{1,i} - x_{1,i+1}) \sin(x_{2,j} - x_{2,j-1})}, & x_{1,i} < x_1 < x_{1,i+1}, x_{2,j-1} < x_2 < x_{2,j}, \\ \frac{\sin(x_1 - x_{1,i+1}) \sin(x_2 - x_{2,j+1})}{\sin(x_{1,i} - x_{1,i+1}) \sin(x_{1,j} - x_{1,j+1})}, & x_{1,i} < x_1 < x_{1,i+1}, x_{2,j} < x_2 < x_{2,j+1}, \\ 0, & \text{otherwise,} \end{cases}$$

$$i = 1, 2, \dots, m - 1, j = 1, 2, \dots, n - 1,$$

where $(x_{1,i}, x_{2,j}) \in \Omega$.

It should be noted that the functions $\varphi_{ij}(x_1, x_2)$ form a finite dimensional linear space in the domain Ω , and therefore these functions are uniquely defined by their values at the nodes $(x_{1,i}, x_{2,j}) \in \Omega$.

To geometrically represent the basis functions $\varphi_{ij}(x_1, x_2)$, $i = 1, 2, \dots, m - 1$, $j = 1, 2, \dots, n - 1$, we present their graphs for the case $m = n = 10$ in Fig.1.

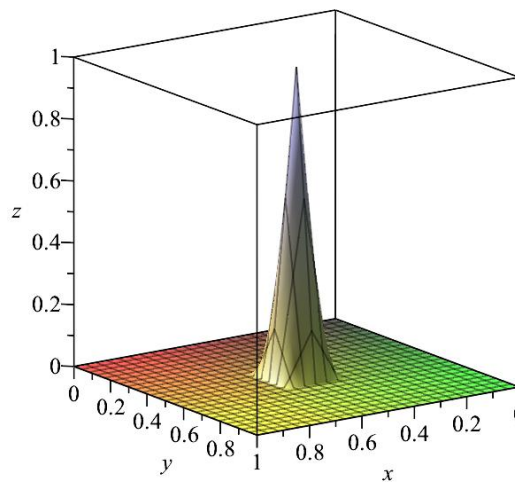


Figure 1. This figure shows the graph of the basis function

figure shows the graph of

$\varphi_{ij}(x_1, x_2)$ ($i = 1, 2, \dots, m - 1, j = 1, 2, \dots, n - 1$).

By employing a system of linearly independent functions $\varphi_{ij}(x_1, x_2)$, a highly accurate approximate solution to the mixed boundary value problem (1)–(3) can be obtained using the finite element method.

References

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